

Attorney's Docket No. K&A 21-1155

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APPLICATION

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FOR UNITED STATES LETTERS PATENT

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SPECIFICATION

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TO ALL WHOM IT MAY CONCERN:

25 BE IT KNOWN THAT I, **JACK A. DENTON**, a citizen of the
UNITED STATES of AMERICA, have invented a new and useful
SYSTEM AND METHOD FOR MONITORING MOVING
EQUIPMENT OPERATIONS of which the following is a
specification:

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SYSTEM AND METHOD FOR MONITORING MOVING EQUIPMENT OPERATIONS

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BACKGROUND OF THE INVENTION

Field of the Invention

10 The present invention relates to systems for monitoring moving equipment work cycles and more particularly pertains to a new system and method for monitoring moving equipment operations for determining operator efficiencies for moving operations.

Description of the Prior Art

20 The use of systems for monitoring moving equipment work cycles is known in the prior art. The area is replete with systems which are operationally coupled to actuators controlling the movements of buckets or blades of moving equipment. These systems are optimized for monitoring the efficiency of the equipment itself.

25 Known prior art includes U.S. Patent No. 5,924,493; U.S. Patent No. 5,944,764; U.S. Patent No. 5,955,706; U.S. Patent No. 5,996,702; U.S. Patent No. 5,964,298; and U.S. Patent No. 5,646,844.

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While these devices fulfill their respective, particular objectives and requirements, the aforementioned patents do not disclose a new system and method for monitoring moving equipment operations. The inventive device includes a position locating assembly coupled to an moving equipment for determining a current position of the moving equipment on an interval basis, a data storage means operationally coupled to the position locating assembly for recording the current position for each interval, and a data processing means for processing and presenting the position information for a user.

In these respects, the system and method for monitoring moving equipment operations according to the present invention substantially departs from the conventional concepts and designs of the prior art, and in so doing provides an apparatus primarily developed for the purpose of determining operator efficiencies for moving operations.

SUMMARY OF THE INVENTION

A major component of any moving project is the efficiency of the individual operators themselves. Preplanned operational, contour or cut maps help direct the operators towards executing the operations in an efficient manner. However, ineffective contouring swaths, inefficient transitions between contouring swaths, and idling increase the overall cost of a contouring project through increased fuel consumption, higher labor expenses due to increased hours, and lost opportunities for other projects. Monitoring of operator actions and post analysis can help develop measurements of individual operator efficiency and provide opportunities for cost reductions.

The general purpose of the present invention, which will be described subsequently in greater detail, is to provide a new system and method for monitoring moving equipment operations apparatus and method which has many of the advantages of the systems for monitoring moving equipment work cycles mentioned heretofore and many novel features that result in a new system and method for monitoring moving equipment operations which is not anticipated, rendered obvious, suggested, or even implied by any of the prior art systems for monitoring moving equipment work cycles, either alone or in any combination thereof.

To attain this, the present invention generally comprises a position locating assembly coupled to an moving equipment for determining a current position of the moving equipment on an interval basis, a data storage means operationally coupled to the position locating assembly for recording the current position for each interval, and a data processing means for processing and presenting the position information for a user.

There has thus been outlined, rather broadly, the more important features of the invention in order that the detailed description thereof that follows may be better understood, and in order that the present contribution to the art may be better appreciated. There are additional features of the invention that will be described hereinafter and which will form the subject matter of the claims appended hereto.

In this respect, before explaining at least one embodiment of the invention in detail, it is to be understood that the invention is not limited in its application to the details of construction and to

the arrangements of the components set forth in the following description or illustrated in the drawings. The invention is capable of other embodiments and of being practiced and carried out in various ways. Also, it is to be understood that the phraseology and 5 terminology employed herein are for the purpose of description and should not be regarded as limiting.

As such, those skilled in the art will appreciate that the conception, upon which this disclosure is based, may readily be 10 utilized as a basis for the designing of other structures, methods and systems for carrying out the several purposes of the present invention. It is important, therefore, that the claims be regarded as including such equivalent constructions insofar as they do not depart from the spirit and scope of the present invention.

15 Further, the purpose of the foregoing abstract is to enable the U.S. Patent and Trademark Office and the public generally, and especially the scientists, engineers and practitioners in the art who are not familiar with patent or legal terms or phraseology, to 20 determine quickly from a cursory inspection the nature and essence of the technical disclosure of the application. The abstract is neither intended to define the invention of the application, which is measured by the claims, nor is it intended to be limiting as to the scope of the invention in any way.

25 It is therefore an object of the present invention to provide a new system and method for monitoring moving equipment operations apparatus and method which has many of the advantages of the systems for monitoring moving equipment work cycles 30 mentioned heretofore and many novel features that result in a new system and method for monitoring moving equipment operations

which is not anticipated, rendered obvious, suggested, or even implied by any of the prior art systems for monitoring moving equipment work cycles, either alone or in any combination thereof.

5 It is another object of the present invention to provide a cost effective means of monitoring operator efficiency which can either be permanently installed onto moving equipment or temporarily coupled to the same for periodic monitoring and assistance as needed.

10 Still another object of the present invention is to provide a new system and method for monitoring moving equipment operations for determining operator efficiencies for moving operations.

15 Yet another object of the present invention is to provide a new system and method for monitoring moving equipment operations which includes a position locating assembly coupled to an moving equipment for determining a current position of the 20 moving equipment on an interval basis, a data storage means operationally coupled to the position locating assembly for recording the current position for each interval, and a data processing means for processing and presenting the position information for a user.

25 These together with other objects of the invention, along with the various features of novelty which characterize the invention, are pointed out with particularity in the claims annexed to and forming a part of this disclosure. For a better understanding of the 30 invention, its operating advantages and the specific objects attained by its uses, reference should be made to the accompanying drawings

and descriptive matter in which there are illustrated preferred embodiments of the invention.

BRIEF DESCRIPTION OF THE DRAWINGS

The invention will be better understood and objects other than those set forth above will become apparent when consideration is given to the following detailed description thereof. Such description makes reference to the annexed drawings wherein:

Figure 1 is a schematic perspective view of a new system and method for monitoring moving equipment operations according to the present invention.

Figure 2 is a schematic perspective view of the position locating assembly of the present invention.

Figure 3 is a schematic perspective view of an embodiment of the visual display unit of the present invention.

Figure 4 is a schematic perspective view of an embodiment of the visual display unit of the present invention.

Figure 5 is a schematic functional interconnect diagram of the position locating assembly of the present invention.

Figure 6 is a process flow diagram of the position locating assembly the present invention.

Figure 7 is a functional interconnect diagram of the present invention.

DESCRIPTION OF THE PREFERRED EMBODIMENT

With reference now to the drawings, and in particular to Figures 1 through 7 thereof, a new system and method for monitoring moving equipment operations embodying the principles and concepts of the present invention and generally designated by the reference numeral 10 will be described.

As best illustrated in Figures 1 through 7, the system and method for monitoring moving equipment operations 10 generally comprises a position locating assembly 20, a data storage means 40, a data processing means 60, a user input device 66, an operational map 62 and a visual display means 70.

The position locating assembly 20 is coupled to a moving equipment 2. Illustrative examples of moving equipments include, but are not limited to a payloader, a road grader, a bull dozer, crane, and road painter. The position locating assembly 20 determines a current position of the moving equipment 2 on an interval basis.

The data storage means 40 is operationally coupled to the position locating assembly 20 for recording the current position for each interval.

The data processing means 60 is used for processing and presenting the position information to a user for analysis.

The user input device 66 is used for providing an indication that the moving equipment 2 is actively operating. The input device 66 is operationally coupled to the data storage means 40 for

recording a start and a stop position for each active use of the moving equipment 2.

The operational map 62 is a representation of the area to be
5 operated upon by the moving equipment 2. The operational map 62 is operationally linked to the position locating assembly 20.

The visual display unit assembly 70 provides a navigation aid to the operator of the moving equipment 2 for facilitating accurate
10 operations on the area in accordance with a predetermined plan.

In a preferred embodiment, the position locating assembly 20 further comprises a housing 21, at least one global positioning system (GPS) receiver 22, and at least one antenna 23. The housing
15 21 may be coupled to the moving equipment 2. The housing 21 includes an interior space. The GPS receiver 22 is positioned substantially within the housing 21 such that the housing 21 provides protection from an external environment. The antenna 23 is operationally coupled to the GPS receiver 22. The antenna 23
20 facilitates reception of GPS signals by the GPS receiver 22.

In an embodiment, the data storage means 40 comprises a compact flash card 41 for providing a transportable nonvolatile storage of the position information for each interval.
25

In a further embodiment, the compact flash card 41 is operationally coupled to the visual display unit 70 for providing a reference grid for navigating through operating by the moving equipment 2 such that a current position as determined by the
30 position locating assembly 20 is compared to the reference grid

facilitates a course correction presented by the visual display unit
70.

Preferably the data processing means 60 further comprises a
5 personal computer 61, an operations map 62, and track software 63.
The personal computer 61 is used for processing the information.
The operations map 62 may be in a machine readable format for
facilitating analysis of paths traveled by the moving equipment 2.
The track software 63 is used for developing an overlay of stored
10 present location information for each interval against the
operations map.

While a personal computer 61 is preferred, a laptop computer,
handheld computer, personal data assistant (PDA), or other similar
15 device can also be used as the data processing means 60.

In an embodiment, the personal computer 61 further comprises
a compact flash card reader 64 for selectively connecting with a
compact flash card 41 for facilitating transporting current position
information for each interval from the position locating assembly
20 20 to the personal computer 61 for facilitating analysis.

In yet a further embodiment, the track software 63 develops a
graphic representation of each swath traveled by the moving
25 equipment 2.

In still a further embodiment, the graphic representation
provides an indication for active use of the moving equipment 2
contrasting from swaths where the moving equipment 2 was not

actively used. The active use is determined by a start and stop indication from the user input device 66.

In yet a further embodiment the graphic representation 5 provides an indication of the moving equipment 2 remaining in a static position for a duration of more than a predetermined number of intervals.

The interval includes a duration of between 1 and 3600 10 seconds inclusive. The interval is determinable prior to operation.

In an embodiment, the visual display unit 70 includes a plurality of light emitting diodes positioned in an array 71 for providing a visual indication of the path to be traveled compared 15 with the swath is taken. Thus, the operator of the moving equipment 2 has a navigation aid on a swath by swath basis.

In a further embodiment, the visual display unit 70 is a liquid crystal display 72 for providing a visual indication of the path to be 20 traveled compared with the swath is taken. Thus, the operator of the moving equipment 2 has a navigation aid on a swath by swath basis.

A volume determining means 30 may be operationally coupled 25 to the data storage means 40 for determining a volume of material is moved by the moving equipment 2.

In an embodiment, the volume determining means 30 further comprises a plurality of sound wave generators 31 and a plurality of 30 sound wave receivers 32. The sound wave generators 31 are for

projecting sound waves against the material being moved. The sound wave receivers 32 are for receiving sound waves, from an associated one of the plurality of sound wave generators 31, bouncing off of the material such that a difference between transmit time and receive time determines a distance traveled. Thus, a volume occupied by the material is determined for each area associated with a pairing of associated sound wave generator 31 and sound wave receiver 32.

In still a further embodiment, the plurality of sound wave generators 31 comprises a plurality of ultrasonic sound wave generators for minimizing environmental effects on the accuracy of the volume determining means. Correspondingly, the plurality of sound wave receivers 32 comprises a plurality of ultrasonic sound wave receivers for minimizing environmental effects on the accuracy of the volume determining means. Each one of the plurality of ultrasonic receivers is operationally paired with an associated one of the ultrasonic sound wave generators.

In an embodiment the data storage means 40 is operationally couplable to the data processing means 60 via a coupling means 50 such that stored information may be transferred to the data processing means 60 from the data storage means 40.

In a further embodiment, the coupling means 50 is a cellular modem system for facilitating periodic updates during a work cycle of the moving equipment 2 for analysis.

Preferably, the data storage means 40 also is for recording supplemental data on an interval basis. Illustratively, the

supplemental data may further comprise, but need not be limited to the volume of material being moved, changes in volume of material, weight of material being moved, material loaded, and material unloaded. The supplemental data is used to augment analysis of the 5 portion and time data for determining efficiency of work cycles.

In use, an operational, contour or cut map is provided for the area to be worked. A series of operation steps for working the area is developed. Preferably, each of these operational steps are 10 developed with start and stop points for facilitating providing a graphic navigational aid for the operator of the moving equipment.

The position locating assembly is coupled to the moving equipment. If a navigation aid is to be provided to the operator, a 15 visual display unit is also coupled to the moving equipment where visible by the operator. The user input device is also coupled to the moving equipment in a convenient location for use by the operator.

20 The interval between measurements is selected from a range of 1 second and 3600 seconds (60 minutes). At the start of each interval or when the user input device is activated the GPS receiver determines the current position of the moving equipment as well as the current time. This position and time data is stored on the 25 compact flash card for later analysis.

After completion of the day's operations, the compact flash card is removed from the position locating assembly and is coupled to a processing means. Typically the processing means will either 30 be a personal computer or a laptop. However, other computing

means may be used such as PDA, programmable calculators, or scheduling tools.

The recorded position and time information for each interval
5 or active use start and stop indications is then overlayed by a track
software with geographic information provided by a geographic
information software operationally available to the processing
means.

10 This overlayed information is then presented to the user for
analysis. Preferably the presentation is performed by graphically
displaying the information on a video monitoring using multiple
colors, symbols, or both to highlight areas where unauthorized
stops, or detours may have occurred. Additionally, a graphic
15 replay of the moving equipments movements throughout the entire
day is possible.

20 As to a further discussion of the manner of usage and
operation of the present invention, the same should be apparent
from the above description. Accordingly, no further discussion
relating to the manner of usage and operation will be provided.

With respect to the above description then, it is to be realized
25 that the optimum dimensional relationships for the parts of the
invention, to include variations in size, materials, shape, form,
function and manner of operation, assembly and use, are deemed
readily apparent and obvious to one skilled in the art, and all
equivalent relationships to those illustrated in the drawings and
30 described in the specification are intended to be encompassed by
the present invention.

Therefore, the foregoing is considered as illustrative only of the principles of the invention. Further, since numerous modifications and changes will readily occur to those skilled in the art, it is not desired to limit the invention to the exact construction and operation shown and described, and accordingly, all suitable modifications and equivalents may be resorted to, falling within the scope of the invention.